

## 6.2 Diagonalizing a Matrix

Note Title

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1. Factor these two matrices into  $A = S\Lambda S^{-1}$ :

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}.$$

(a) Find  $\lambda$ 's:  $\begin{vmatrix} 1-\lambda & 2 \\ 0 & 3-\lambda \end{vmatrix} = 0$

$$\therefore (\lambda-3)(\lambda-1) = 0 \Rightarrow \lambda = 1, 3$$

Find eigenvectors:

$$\begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 1 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \therefore \begin{aligned} 3x_2 &= x_2 \Rightarrow x_2 = 0 \\ x_1 + 2x_2 &= x_1 + x_2 \\ &\Rightarrow x_1 = x_1. \end{aligned}$$

$$\therefore \lambda = 1: c \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 3 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow \begin{aligned} x_1 + 2x_2 &= 3x_1, x_1 = x_2 \\ 3x_2 &= 3x_2 \end{aligned}$$

$$\therefore \lambda = 3: c \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\therefore S = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \quad \therefore S^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$\therefore A = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$(b) \lambda\text{'s} : \begin{vmatrix} 1-\lambda & 1 \\ 2 & 2-\lambda \end{vmatrix} = 0, \quad (\lambda-2)(\lambda-1)-2=0 \\ \lambda^2-3\lambda=0$$

$$\therefore \lambda = 0, 3$$

Eigenvectors:

$$\lambda = 0 : \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad \begin{aligned} x_1 + x_2 &= 0 \\ x_1 &= -x_2 \end{aligned}$$

$$\therefore c \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\lambda = 3 : \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3x_1 \\ 3x_2 \end{bmatrix} \quad \begin{aligned} x_1 + x_2 &= 3x_1 \\ 2x_1 + 2x_2 &= 3x_2 \end{aligned}$$

$$\therefore x_2 = 2x_1, \quad \therefore c \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\therefore S = \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}, \quad S^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}$$

$$\therefore A = S \Lambda S^{-1} = \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 2/3 & -1/3 \\ 1/3 & 1/3 \end{bmatrix}$$

2. If  $A = SAS^{-1}$  then  $A^3 = ( ) ( ) ( )$  and  $A^{-1} = ( ) ( ) ( )$ .

$$(a) A^2 = (S\Lambda S^{-1})(S\Lambda S^{-1}) = S\Lambda S^{-1}S\Lambda S^{-1} \\ = S\Lambda^2 S^{-1}$$

$$\therefore A^3 = \underline{S\Lambda^3 S^{-1}}$$

$$(b) A = SAS^{-1} \Rightarrow A^{-1} = (S\Lambda S^{-1})^{-1} = \underline{S\Lambda^{-1} S^{-1}},$$

if  $\Lambda$  is invertible.

3. If  $A$  has  $\lambda_1 = 2$  with eigenvector  $x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\lambda_2 = 5$  with  $x_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , use  $SAS^{-1}$  to find  $A$ . No other matrix has the same  $\lambda$ 's and  $x$ 's.

$$S = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \Lambda = \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}, S^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$\therefore A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 \\ 0 & 5 \end{bmatrix} = \underline{\underline{\begin{bmatrix} 2 & 3 \\ 0 & 5 \end{bmatrix}}}$$

5. True or false: If the columns of  $S$  (eigenvectors of  $A$ ) are linearly independent, then

- (a)  $A$  is invertible      (b)  $A$  is diagonalizable  
(c)  $S$  is invertible      (d)  $S$  is diagonalizable.

(a)  $A$  may not be invertible if one of the  $\lambda$ 's is 0.  $\therefore$  False.

(b) This is GD:  $A = S^{-1}AS$ , or

$$AS = [\lambda_1 x_1 \dots \lambda_n x_n] = S [\lambda_1 \dots \lambda_n] = SA.$$

$\therefore$  True.

(c) True

(d) False: just because a matrix is invertible doesn't mean there are eigenvectors.

i.e., Suppose  $\det A \neq 0$ .  $\det(A - \lambda I) = 0$  may not have any real roots.

$\therefore$  over the field of reals, there may be no eigenvectors,  $\therefore$  can't diagonalize.

8.

Write down the most general matrix that has eigenvectors  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ .

$$\text{Consider } \begin{bmatrix} a & c \\ b & d \end{bmatrix}. \quad \therefore \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \lambda_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \lambda_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} \lambda_2 \\ -\lambda_2 \end{bmatrix}$$

$$\begin{aligned} \therefore a+c &= \lambda_1, & a-c &= \lambda_2 \\ b+d &= \lambda_1, & b-d &= -\lambda_2 \end{aligned}$$

$$2a = \lambda_1 + \lambda_2 \quad a = \frac{\lambda_1 + \lambda_2}{2}$$

$$2b = \lambda_1 - \lambda_2 \quad b = \frac{\lambda_1 - \lambda_2}{2}$$

$$2c = \lambda_1 - \lambda_2 \quad c = \frac{\lambda_1 - \lambda_2}{2}$$

$$2d = \lambda_1 + \lambda_2 \quad d = \frac{\lambda_1 + \lambda_2}{2}$$

$$\therefore a=d, \quad b=c, \quad \text{so } \underline{\underline{\begin{bmatrix} a & b \\ b & a \end{bmatrix}}}$$

18. The matrix  $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$  is not diagonalizable because the rank of  $A - 3I$  is \_\_\_\_\_.  
Change one entry to make  $A$  diagonalizable. Which entries could you change?

Note  $\det(A - \lambda I) = (3 - \lambda)^2$ , so look at  $A - 3I$ ,  
its rank is 1, so dim nullspace is 1,  
so can't have two independent eigenvectors.  
 $\therefore$  not diagonalizable.

Changing  $a_{11}$ ,  $a_{21}$ , or  $a_{22}$  can make  
 $\det(A - \lambda I)$  have two different roots.

Changing  $a_{12}$  won't change determinant.

20. (Recommended) Find  $\Lambda$  and  $S$  to diagonalize  $A$  in Problem 19. What is the limit of  $\Lambda^k$  as  $k \rightarrow \infty$ ? What is the limit of  $S\Lambda^k S^{-1}$ ? In the columns of this limiting matrix you see the \_\_\_\_\_.

$$(a) A = \begin{bmatrix} .6 & .4 \\ .4 & .6 \end{bmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} .6 - \lambda & .4 \\ .4 & .6 - \lambda \end{vmatrix}$$

$$= \lambda^2 - 1.2\lambda + 0.36 - 0.16$$

$$= \lambda^2 - 1.2\lambda + .20$$

$$= (\lambda - 1.0)(\lambda - 0.2)$$

$$\therefore \lambda = 1, 0.2 \quad \therefore \Lambda = \begin{bmatrix} 1 & 0 \\ 0 & 0.2 \end{bmatrix}$$

$$\text{Eigenvectors: } \lambda = 1 \quad \begin{bmatrix} -.4 & .4 \\ .4 & -.4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left. \begin{array}{l} -.4x + .4y = 0 \\ .4x - .4y = 0 \end{array} \right\} x = y$$

$$\therefore \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda = 0.2 \quad \begin{bmatrix} .4 & -4 \\ .4 & .4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left. \begin{array}{l} .4x + .4y = 0 \\ -4x + .4y = 0 \end{array} \right\} x = -y$$

$$\therefore \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\therefore S = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}, \quad S^{-1} = -\frac{1}{2} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\therefore A = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0.2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$(b) \lim_{K \rightarrow \infty} A^K = \lim_{K \rightarrow \infty} \begin{bmatrix} 1 & 0 \\ 0 & 0.2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$(c) \lim_{K \rightarrow \infty} S A^K S^{-1} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

This is the steady state.

24.

Suppose that  $A = SAS^{-1}$ . Take determinants to prove that  $\det A = \lambda_1 \lambda_2 \cdots \lambda_n =$  product of  $\lambda$ 's. This quick proof only works when  $A$  is \_\_\_\_\_.

$$\begin{aligned}
\det A &= \det(S) \det(\Lambda) \det(S^{-1}) \\
&= \det(S) \det(S^{-1}) \det(\Lambda) \\
&= \det(SS^{-1}) \det(\Lambda) \\
&= \det(I) \det(\Lambda) \\
&= \det(\Lambda) = \lambda_1 \lambda_2 \cdots \lambda_n
\end{aligned}$$

Only works when  $A$  is diagonalizable.

30.

(Recommended) Suppose  $Ax = \lambda x$ . If  $\lambda = 0$  then  $x$  is in the nullspace. If  $\lambda \neq 0$  then  $x$  is in the column space. Those spaces have dimensions  $(n-r) + r = n$ . So why doesn't every square matrix have  $n$  linearly independent eigenvectors?

$x$  (solutions to  $Ax = 0 \cdot x$ ) will give  $n-r$  independent eigenvectors.

For  $\lambda \neq 0$ , solutions to  $Ax = \lambda x$  may not give  $r$  independent eigenvectors.